# STA 360/602L: MODULE 2.6

#### LOSS FUNCTIONS AND BAYES RISK

DR. OLANREWAJU MICHAEL AKANDE



#### **B**AYES ESTIMATE

- As we've seen by now, having posterior distributions instead of onenumber summaries is great for capturing uncertainty.
- That said, it is still very appealing to have simple summaries, especially when dealing with clients or collaborators from other fields, who desire one.
- Can we obtain a single estimate of  $\theta$  based on the posterior? Sure!
- **Bayes estimate** is the value  $\hat{\theta}$ , that minimizes the Bayes risk.



#### **B**AYES ESTIMATE

- Bayes risk is defined as the expected loss averaged over the posterior distribution.
- Put differently, a Bayes estimate  $\hat{\theta}$  has the lowest posterior expected loss.
- That's fine, but what does expected loss mean?
- Frequentist risk also exists but we won't go into that here.



#### LOSS FUNCTIONS

- A loss function L(θ, δ(y)) is a function of a parameter θ, where δ(y) is some decision about θ, based on just the data y.
- For example, δ(y) = ȳ can be the decision to use the sample mean to estimate θ, the true population mean.
- L(θ, δ(y)) determines the penalty for making the decision δ(y), if θ is the true parameter; L(θ, δ(y)) characterizes the price paid for errors.



#### LOSS FUNCTIONS

 A common choice for example, when dealing with point estimation, is the squared error loss, which has

$$L( heta, \delta(y)) = ( heta - \delta(y))^2.$$

Bayes risk is thus

$$ho( heta,\delta) = \mathbb{E}\left[ \left[ \left. L( heta,\delta(y)) 
ight. |y] 
ight] = \int L( heta,\delta(y)) \cdot \pi( heta|y) \ d heta,$$

and we proceed to find the value  $\hat{\theta}$ , that is, the decision  $\delta(y)$ , that minimizes the Bayes risk.



# BAYES ESTIMATOR UNDER SQUARED ERROR LOSS

- Turns out that, under squared error loss, the decision  $\delta(y)$  that minimizes the posterior risk is the posterior mean.
- Proof: Let  $L(\theta, \delta(y)) = (\theta \delta(y))^2$ . Then,

$$egin{aligned} &
ho( heta,\delta) = \int L( heta,\delta(y))\cdot\pi( heta|y)\;d heta.\ &= \int ( heta-\delta(y))^2\cdot\pi( heta|y)\;d heta. \end{aligned}$$

- Expand, then take the partial derivative of  $\rho(\theta, \delta)$  with respect to  $\delta(y)$ .
- To be continued on the board!



## BAYES ESTIMATOR UNDER SQUARED ERROR LOSS

$$p( heta,\delta)\int ( heta-\delta(y))^2\cdot\pi( heta|y)\;d heta.$$

- Easy to see then that  $\delta(y) = \mathbb{E}[ heta|x]$  is the minimizer.
- Well that's great! The posterior mean is often very easy to calculate in most cases.
- In the beta-binomial case for example, the Bayes estimate under squared error loss is just

$$\hat{ heta}=rac{a+y}{a+b+n},$$

the posterior mean.



### WHAT ABOUT OTHER LOSS FUNCTIONS?

 Clearly, squared error is only one possible loss function. An alternative is absolute loss, which has

 $L( heta,\delta(y))=| heta-\delta(y)|.$ 

- Absolute loss places less of a penalty on large deviations & the resulting Bayes estimate is **posterior median**.
- Median is actually relatively easy to estimate.



#### WHAT ABOUT OTHER LOSS FUNCTIONS?

 Recall that for a continuous random variable Y with cdf F, the median of the distribution is the value z, which satisfies

$$F(z)=\Pr(Y\leq z)=rac{1}{2}=\Pr(Y\geq z)=1-F(z).$$

- As long as we know how to evaluate the CDF of the distribution we have, we can solve for z.
- Think R!



### WHAT ABOUT OTHER LOSS FUNCTIONS?

 For the beta-binomial model, the CDF of the beta posterior can be written as

$$F(z)=\Pr( heta\leq z|y)=\int_0^z ext{Beta}( heta|a+y,b+n-y)d heta.$$

- Then, if  $\hat{\theta}$  is the median, we have that  $F(\hat{\theta}) = 0.5$ .
- To solve for  $\hat{\theta}$ , apply the inverse CDF  $\hat{\theta} = F^{-1}(0.5)$ .
- In R, that's simply

```
qbeta(0.5,a+y,b+n-y)
```

• For other popular distributions, switch out the beta.



#### LOSS FUNCTIONS AND DECISIONS

- Loss functions are not specific to estimation problems but are a critical part of decision making.
- For example, suppose you are deciding how much money to bet (\$A) on Duke in the next UNC-Duke men's basketball game.
- Suppose, if Duke
  - loses (y = 0), you lose the amount you bet (\$A)
  - wins (y = 1), you gain B per \$1 bet
- What is a good sampling distribution for y here?
- Then, the loss function can be characterized as

L(A, y) = A(1 - y) - y(BA),

with your action being the amount bet A.

When will your bet be "rational"?

y is an unknown state, but we can think of it as a new prediction y<sub>n+1</sub> given that we have data from win-loss records (y<sub>1:n</sub>) that can be converted into a Bayesian posterior,

 $heta \sim ext{beta}(a_n, b_n),$ 

with this posterior concentrated slightly to the left of 0.5, if we only use data on UNC-Duke games (UNC men lead Duke 139-112 all time).

- Actually, it might make more sense to focus on more recent head-to-head data and not the all time record.
- In fact, we might want to build a model that predicts the outcome of the game using historical data & predictors (current team rankings, injuries, etc).
- However, to keep it simple for this illustration, go with the posterior above.



• The Bayes risk for action A is then the expectation of the loss function,

 $ho(A) = \mathbb{E}\left[ \left. L(A,y) 
ight| y_{1:n} 
ight].$ 

- To calculate this as a function of A and find the optimal A, we need to marginalize over the **posterior predictive distribution** for y.
- Why are we using the posterior predictive distribution here instead of the posterior distribution?
- As an aside, recall from Module 2.3 that

$$p(y_{n+1}|y_{1:n})=rac{a_n^{y_{n+1}}b_n^{1-y_{n+1}}}{a_n+b_n}; \hspace{0.3cm} y_{n+1}=0,1.$$

• Specifically, that the posterior predictive distribution here is  $\text{Bernoulli}(\hat{\theta})$ , with

$$\hat{ heta} = rac{a_n}{a_n+b_n}$$

By the way, what do a<sub>n</sub> and b<sub>n</sub> represent?

• With the loss function L(A, y) = A(1 - y) - y(BA), and using the notation  $y_{n+1}$  instead of y (to make it obvious the game has not been played), the Bayes risk (expected loss) for bet A is

$$egin{aligned} &
ho(A) = \mathbb{E}\left[ \left. L(A,y_{n+1}) \; | y_{1:n} 
ight] \ &= \mathbb{E}\left[ A(1-y_{n+1}) - y_{n+1}(BA) \; | y_{1:n} 
ight] \ &= A \; \mathbb{E}\left[ 1 - y_{n+1} | \; y_{1:n} 
ight] - (BA) \; \mathbb{E}\left[ y_{n+1} | y_{1:n} 
ight] \ &= A \; \left( 1 - \mathbb{E}\left[ y_{n+1} | y_{1:n} 
ight] 
ight) - (BA) \; \mathbb{E}\left[ y_{n+1} | y_{1:n} 
ight] \ &= A \; \left( 1 - \mathbb{E}\left[ y_{n+1} | y_{1:n} 
ight] 
ight) - (BA) \; \mathbb{E}\left[ y_{n+1} | y_{1:n} 
ight] \ &= A \; \left( 1 - \mathbb{E}\left[ y_{n+1} | y_{1:n} 
ight] \; (1+B) 
ight). \end{aligned}$$



F

Hence, your bet is rational as long as

$$\mathbb{E}\left[y_{n+1} \mid y_{1:n}
ight](1+B) > 1 \ = rac{a_n(1+B)}{a_n+b_n} > 1.$$

- Clearly, there is no limit to the amount you should bet if this condition is satisfied (the loss function is clearly too simple).
- Loss function needs to be carefully chosen to lead to a good decision finite resources, diminishing returns, limits on donations, etc.
- Want more on loss functions, expected loss/utility, or decision problems in general? Consider taking a course on decision theory (STA623?).



## WHAT'S NEXT?

#### MOVE ON TO THE READINGS FOR THE NEXT MODULE!

