STA 360/602L: MODULE 2.6

LOSS FUNCTIONS AND BAYES RISK

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BAYES ESTIMATE

- As we've seen by now, having posterior distributions instead of onenumber summaries is great for capturing uncertainty.
- That said, it is still very appealing to have simple summaries, especially when dealing with clients or collaborators from other fields, who desire one.
- Can we obtain a single estimate of θ based on the posterior? Sure!
- Bayes estimate is the value $\hat{\theta}$, that minimizes the Bayes risk. \blacksquare

BAYES ESTIMATE

- Bayes risk is defined as the expected loss averaged over the posterior distribution.
- Put differently, a Bayes estimate $\hat{\theta}$ has the lowest posterior expected loss.
- That's fine, but what does expected loss mean?
- Frequentist risk also exists but we won't go into that here.

LOSS FUNCTIONS

- A loss function $L(\theta, \delta(y))$ is a function of a parameter θ , where $\delta(y)$ is some decision about θ , based on just the data y .
- For example, $\delta(y)=\bar{y}$ can be the decision to use the sample mean to estimate θ , the true population mean.
- $L(\theta, \delta(y))$ determines the penalty for making the decision $\delta(y)$, if θ is the true parameter; $L(\theta, \delta(y))$ characterizes the price paid for errors.

LOSS FUNCTIONS

A common choice for example, when dealing with point estimation, is the squared error loss, which has

$$
L(\theta,\delta(y))=(\theta-\delta(y))^2.
$$

Bayes risk is thus

$$
\rho(\theta,\delta) = \mathbb{E}\left[\ L(\theta,\delta(y))\ |y\right] = \int L(\theta,\delta(y))\cdot \pi(\theta|y)\ d\theta,
$$

and we proceed to find the value $\hat{\theta}$, that is, the decision $\delta(y)$, that minimizes the Bayes risk.

BAYES ESTIMATOR UNDER SQUARED ERROR LOSS

- Turns out that, under squared error loss, the decision $\delta(y)$ that minimizes the posterior risk is the posterior mean.
- Proof: Let $L(\theta, \delta(y)) = (\theta \delta(y))^2$. Then,

$$
\rho(\theta,\delta) = \int L(\theta,\delta(y)) \cdot \pi(\theta|y) d\theta.
$$

=
$$
\int (\theta - \delta(y))^2 \cdot \pi(\theta|y) d\theta.
$$

- Expand, then take the partial derivative of $\rho(\theta, \delta)$ with respect to $\delta(y)$.
- \blacksquare To be continued on the board!

BAYES ESTIMATOR UNDER SQUARED ERROR LOSS

$$
\rho(\theta,\delta)\int (\theta-\delta(y))^2\cdot\pi(\theta|y)\;d\theta.
$$

- Easy to see then that $\delta(y) = \mathbb{E}[\theta|x]$ is the minimizer.
- Well that's great! The posterior mean is often very easy to calculate in most cases.
- In the beta-binomial case for example, the Bayes estimate under squared \blacksquare error loss is just

$$
\hat{\theta} = \frac{a+y}{a+b+n},
$$

the posterior mean.

 \Box

WHAT ABOUT OTHER LOSS FUNCTIONS?

Clearly, squared error is only one possible loss function. An alternative is absolute loss, which has

 $L(\theta, \delta(y)) = |\theta - \delta(y)|.$

- Absolute loss places less of a penalty on large deviations & the resulting Bayes estimate is **posterior median**.
- Median is actually relatively easy to estimate.

WHAT ABOUT OTHER LOSS FUNCTIONS?

Recall that for a continuous random variable Y with cdf F , the median of the distribution is the value z , which satisfies

$$
F(z)=\Pr(Y\leq z)=\frac{1}{2}=\Pr(Y\geq z)=1-F(z).
$$

- As long as we know how to evaluate the CDF of the distribution we have, we can solve for z .
- **Think R!**

WHAT ABOUT OTHER LOSS FUNCTIONS?

For the beta-binomial model, the CDF of the beta posterior can be written as

$$
F(z) = \Pr(\theta \leq z | y) = \int_0^z \text{Beta}(\theta | a+y, b+n-y) d\theta.
$$

- Then, if $\hat{\theta}$ is the median, we have that $F(\hat{\theta}) = 0.5.$
- To solve for $\hat{\theta}$, apply the inverse CDF $\hat{\theta} = F^{-1}(0.5).$
- \blacksquare In R, that's simply

```
qbeta(0.5, a+y, b+n-y)
```
For other popular distributions, switch out the beta.

LOSS FUNCTIONS AND DECISIONS

- Loss functions are not specific to estimation problems but are a critical \blacksquare part of decision making.
- For example, suppose you are deciding how much money to bet (\$A) on Duke in the next UNC-Duke men's basketball game.
- Suppose, if Duke
	- \blacksquare loses (y = 0), you lose the amount you bet (\$A)
	- wins $(y = 1)$, you gain B per \$1 bet
- What is a good sampling distribution for y here?
- Then, the loss function can be characterized as

 $L(A, y) = A(1 - y) - y(BA),$

with your action being the amount bet A.

When will your bet be "rational"?

 y is an unknown state, but we can think of it as a new prediction y_{n+1} given that we have data from win-loss records $(y_{1:n})$ that can be converted into a Bayesian posterior,

$\theta \sim \text{beta}(a_n, b_n),$

with this posterior concentrated slightly to the left of 0.5, if we only use data on UNC-Duke games (UNC men lead Duke 139-112 all time).

- Actually, it might make more sense to focus on more recent head-to-head data and not the all time record.
- \blacksquare In fact, we might want to build a model that predicts the outcome of the game using historical data & predictors (current team rankings, injuries, etc).
- However, to keep it simple for this illustration, go with the posterior \blacksquare above.

The Bayes risk for action A is then the expectation of the loss function,

 $\rho(A) = \mathbb{E} [L(A, y) | y_{1:n}]$.

- To calculate this as a function of A and find the optimal A , we need to marginalize over the **posterior predictive distribution** for y.
- Why are we using the posterior predictive distribution here instead of the \blacksquare posterior distribution?
- As an aside, recall from Module 2.3 that

$$
p(y_{n+1}|y_{1:n})=\frac{a_n^{y_{n+1}}b_n^{1-y_{n+1}}}{a_n+b_n};\quad y_{n+1}=0,1.
$$

Specifically, that the posterior predictive distribution here is $\mathrm{Bernoulli}(\hat{\theta})$, with

$$
\hat{\theta} = \frac{a_n}{a_n + b_n}
$$

By the way, what do a_n and b_n represent?

With the loss function $L(A, y) = A(1 - y) - y(BA)$, and using the notation y_{n+1} instead of y (to make it obvious the game has not been played), the Bayes risk (expected loss) for bet A is

$$
\begin{array}{l} \rho(A)=\mathbb{E}\left[\ L(A,y_{n+1})\ |y_{1:n}\right] \\\\qquad=\mathbb{E}\left[A(1-y_{n+1})-y_{n+1}(BA)\ |y_{1:n}\right] \\\\qquad=\ A\ \mathbb{E}\left[1-y_{n+1}|\ y_{1:n}\right]-(BA)\ \mathbb{E}\left[y_{n+1}|y_{1:n}\right] \\\\qquad=\ A\ \left(1-\mathbb{E}\left[y_{n+1}|y_{1:n}\right]\right) -\left(BA\right)\ \mathbb{E}\left[y_{n+1}|y_{1:n}\right] \\\\qquad=\ A\ \left(1-\mathbb{E}\left[y_{n+1}|y_{1:n}\right]\ \left(1+B\right)\right).\end{array}
$$

Hence, your bet is rational as long as

$$
\mathbb{E}\left[y_{n+1}\right|y_{1:n}\right](1+B) > 1
$$

$$
\frac{a_n(1+B)}{a_n+b_n} > 1.
$$

- Clearly, there is no limit to the amount you should bet if this condition is satisfied (the loss function is clearly too simple).
- Loss function needs to be carefully chosen to lead to a good decision \blacksquare finite resources, diminishing returns, limits on donations, etc.
- Want more on loss functions, expected loss/utility, or decision problems in general? Consider taking a course on decision theory (STA623?).

WHAT'S NEXT?

MOVE ON TO THE READINGS FOR THE NEXT MODULE!

