

STA 360/602L: MODULE 4.6

MISSING DATA AND IMPUTATION II

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BAYESIAN INFERENCE WITH MISSING DATA

- As we have seen, for MCAR and MAR, we can focus on $p(\mathbf{Y}_{obs}|\boldsymbol{\theta}, \Sigma)$ in the likelihood function, when inferring $(\boldsymbol{\theta}, \Sigma)$.
- While this is great, for posterior sampling under most models (especially multivariate models), we actually do need all the \mathbf{Y} 's to update the parameters.
- In addition, we may actually want to learn about the missing values, in addition to inferring $(\boldsymbol{\theta}, \Sigma)$.
- By thinking of the missing data as **another set of parameters**, we can sample them from the "posterior predictive" distribution of the missing data conditional on the observed data and parameters:

$$p(\mathbf{Y}_{mis}|\mathbf{Y}_{obs}, \boldsymbol{\theta}, \Sigma) \propto \prod_{i=1}^n p(\mathbf{Y}_{i,mis}|\mathbf{Y}_{i,obs}, \boldsymbol{\theta}, \Sigma).$$

- In the case of the multivariate model, each $p(\mathbf{Y}_{i,mis}|\mathbf{Y}_{i,obs}, \boldsymbol{\theta}, \Sigma)$ is just a normal distribution, and we can leverage results on conditional distributions for normal models.

GIBBS SAMPLER WITH MISSING DATA

At iteration $s + 1$, do the following

1. Sample $\boldsymbol{\theta}^{(s+1)}$ from its multivariate normal full conditional

$$p(\boldsymbol{\theta}^{(s+1)} | \mathbf{Y}_{obs}, \mathbf{Y}_{mis}^{(s)}, \Sigma^{(s)}).$$

2. Sample $\Sigma^{(s+1)}$ from its inverse-Wishart full conditional

$$p(\Sigma^{(s+1)} | \mathbf{Y}_{obs}, \mathbf{Y}_{mis}^{(s)}, \boldsymbol{\theta}^{(s+1)}).$$

3. For each $i = 1, \dots, n$, with at least one zero value in the missingness indicator vector \mathbf{R}_i , sample $\mathbf{Y}_{i,mis}^{(s+1)}$ from the full conditional

$$p(\mathbf{Y}_{i,mis}^{(s+1)} | \mathbf{Y}_{i,obs}, \boldsymbol{\theta}^{(s+1)}, \Sigma^{(s+1)}),$$

which is also multivariate normal, with its form derived from the original sampling model but with the updated parameters, that is,
 $\mathbf{Y}_i^{(s+1)} = (\mathbf{Y}_{i,obs}, \mathbf{Y}_{i,mis}^{(s+1)})^T \sim \mathcal{N}_p(\boldsymbol{\theta}^{(s+1)}, \Sigma^{(s+1)}).$

GIBBS SAMPLER WITH MISSING DATA

- Rewrite $\mathbf{Y}_i^{(s+1)} = (\mathbf{Y}_{i,mis}, \mathbf{Y}_{i,obs}^{(s+1)})^T \sim \mathcal{N}_p(\boldsymbol{\theta}^{(s+1)}, \Sigma^{(s+1)})$ as

$$\mathbf{Y}_i = \begin{pmatrix} \mathbf{Y}_{i,mis} \\ \mathbf{Y}_{i,obs} \end{pmatrix} \sim \mathcal{N}_p \left[\begin{pmatrix} \boldsymbol{\theta}_1 \\ \boldsymbol{\theta}_2 \end{pmatrix}, \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix} \right],$$

so that we can take advantage of the conditional normal results.

- That is, we have

$$\mathbf{Y}_{i,mis} | \mathbf{Y}_{i,obs} = \mathbf{y}_{i,obs} \sim \mathcal{N} \left(\boldsymbol{\theta}_1 + \Sigma_{12} \Sigma_{22}^{-1} (\mathbf{y}_{i,obs} - \boldsymbol{\theta}_2), \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21} \right).$$

as the multivariate normal distribution (or univariate normal distribution if \mathbf{Y}_i only has one missing entry) we need in step 3 of the Gibbs sampler.

- This sampling technique actually encodes MAR since the imputations for \mathbf{Y}_{mis} depend on the \mathbf{Y}_{obs} .
- Now let's revisit the reading comprehension example again. We will add missing values to the original data and refit the model.

READING EXAMPLE WITH MISSING DATA

```
Y <- as.matrix(dget("http://www2.stat.duke.edu/~pdh10/FCBS/Inline/Y.reading"))

#Add 20% missing data; MCAR
set.seed(1234)
Y_WithMiss <- Y #So we can keep the full data
Miss_frac <- 0.20
R <- matrix(rbinom(nrow(Y_WithMiss)*ncol(Y_WithMiss),1, Miss_frac),
             nrow(Y_WithMiss),ncol(Y_WithMiss))
Y_WithMiss[R==1]<-NA
Y_WithMiss[1:12,]
```

```
##      pretest posttest
## [1,]      59      77
## [2,]      43      39
## [3,]      34      46
## [4,]      32      NA
## [5,]      NA      38
## [6,]      38      NA
## [7,]      55      NA
## [8,]      67      86
## [9,]      64      77
## [10,]     45      60
## [11,]     49      50
## [12,]     72      59
```

```
colMeans(is.na(Y_WithMiss))
```

```
##      pretest posttest
## 0.1363636 0.2272727
```

READING EXAMPLE WITH MISSING DATA

```
#ACTUAL ANALYSIS STARTS HERE!!!
#Data dimensions
n <- nrow(Y_WithMiss); p <- ncol(Y_WithMiss)

#Hyperparameters for the priors
mu_0 <- c(50,50)
Lambda_0 <- matrix(c(156,78,78,156),nrow=2,ncol=2)
nu_0 <- 4
S_0 <- matrix(c(625,312.5,312.5,625),nrow=2,ncol=2)

#Define missing data indicators
##we already know R. This is to write a more general code for when we don't
R <- 1*(is.na(Y_WithMiss))
R[1:12,]

##      pretest posttest
## [1,]      0      0
## [2,]      0      0
## [3,]      0      0
## [4,]      0      1
## [5,]      1      0
## [6,]      0      1
## [7,]      0      1
## [8,]      0      0
## [9,]      0      0
## [10,]     0      0
## [11,]     0      0
## [12,]     0      0
```

READING EXAMPLE WITH MISSING DATA

```
#Initial values for Gibbs sampler
Y_Full <- Y_WithMiss #So we can keep the data with missing values as is
for (j in 1:p) {
  Y_Full[is.na(Y_Full[,j]),j] <- mean(Y_Full[,j],na.rm=TRUE) #start with mean imputation
}

Sigma <- S_0 # can't really rely on cov(Y) because we don't have full Y

#Set null objects to save samples
THETA_WithMiss <- NULL
SIGMA_WithMiss <- NULL
Y_MISS <- NULL

#first set number of iterations and burn-in, then set seed
n_iter <- 10000; burn_in <- 0.3*n_iter
```

GIBBS SAMPLER WITH MISSING DATA

```
#library(mvtnorm) for multivariate normal
#library(MCMCpack) for inverse-Wishart

Lambda_0_inv <- solve(Lambda_0) #move outside sampler since it does not change

for (s in 1:(n_iter+burn_in)){
  ##first we must recalculate ybar inside the loop now since it changes every iteration
  ybar <- apply(Y_Full,2,mean)

  ##update theta
  Sigma_inv <- solve(Sigma) #invert once
  Lambda_n <- solve(Lambda_0_inv + n*Sigma_inv)
  mu_n <- Lambda_n %*% (Lambda_0_inv%*%mu_0 + n*Sigma_inv%*%ybar)
  theta <- rmvnorm(1,mu_n,Lambda_n)

  ##update Sigma
  S_theta <- (t(Y_Full)-c(theta))%*%t(t(Y_Full)-c(theta))
  S_n <- S_0 + S_theta
  nu_n <- nu_0 + n
  Sigma <- riwish(nu_n, S_n)
```

GIBBS SAMPLER WITH MISSING DATA

```
##update missing data using updated draws of theta and Sigma
for(i in 1:n) {
  if(sum(R[i,]>0)){
    obs_index <- R[i,]==0
    mis_index <- R[i,]==1
    Sigma_22_obs_inv <- solve(Sigma[obs_index,obs_index]) #invert just once
    Sigma_12_Sigma_22_obs_inv <- Sigma[mis_index,obs_index] %*% Sigma_22_obs_inv

    Sigma_cond_mis <- Sigma[mis_index,mis_index] -
      Sigma_12_Sigma_22_obs_inv %*% Sigma[obs_index,mis_index]

    mu_cond_mis <- theta[mis_index] +
      Sigma_12_Sigma_22_obs_inv %*% (t(Y_Full[i,obs_index])-theta[obs_index])

    Y_Full[i,mis_index] <- rmvnorm(1,mu_cond_mis,Sigma_cond_mis)
  }
}

#save results only past burn-in
if(s > burn_in){
  THETA_WithMiss <- rbind(THETA_WithMiss,theta)
  SIGMA_WithMiss <- rbind(SIGMA_WithMiss,c(Sigma))
  Y_MISS <- rbind(Y_MISS, Y_Full[R==1] )
}
}

colnames(THETA_WithMiss) <- c("theta_1","theta_2")
colnames(SIGMA_WithMiss) <- c("sigma_11","sigma_12","sigma_21","sigma_22") #symmetry in sig
```

DIAGNOSTICS

```
#library(coda)
THETA_WithMiss.mcmc <- mcmc(THETA_WithMiss,start=1); summary(THETA_WithMiss.mcmc)

##
## Iterations = 1:10000
## Thinning interval = 1
## Number of chains = 1
## Sample size per chain = 10000
##
## 1. Empirical mean and standard deviation for each variable,
##     plus standard error of the mean:
##
##          Mean      SD Naive SE Time-series SE
## theta_1 45.64 3.012  0.03012       0.03276
## theta_2 54.15 3.453  0.03453       0.03939
##
## 2. Quantiles for each variable:
##
##          2.5%    25%    50%    75%   97.5%
## theta_1 39.60 43.65 45.62 47.64 51.55
## theta_2 47.31 51.91 54.17 56.45 61.08
```

DIAGNOSTICS

```
SIGMA_WithMiss.mcmc <- mcmc(SIGMA_WithMiss,start=1); summary(SIGMA_WithMiss.mcmc)
```

```
##  
## Iterations = 1:10000  
## Thinning interval = 1  
## Number of chains = 1  
## Sample size per chain = 10000  
##  
## 1. Empirical mean and standard deviation for each variable,  
##     plus standard error of the mean:  
##  
##           Mean      SD Naive SE Time-series SE  
## sigma_11 194.8 62.89      0.6289      0.6063  
## sigma_12 152.1 60.58      0.6058      0.6910  
## sigma_21 152.1 60.58      0.6058      0.6910  
## sigma_22 247.7 83.55      0.8355      0.9659  
##  
## 2. Quantiles for each variable:  
##  
##           2.5%    25%    50%    75% 97.5%  
## sigma_11 108.30 151.2 182.5 224.4 348.6  
## sigma_12  64.76 110.3 141.9 182.0 299.6  
## sigma_21  64.76 110.3 141.9 182.0 299.6  
## sigma_22 133.33 189.3 231.8 289.0 450.8
```

COMPARE TO INFERENCE FROM FULL DATA

With missing data:

```
apply(THETA_WithMiss, 2, summary)
```

```
##          theta_1   theta_2
## Min.    32.64839 41.13748
## 1st Qu. 43.65457 51.90859
## Median  45.61740 54.16720
## Mean    45.63740 54.14929
## 3rd Qu. 47.64129 56.45068
## Max.    58.65830 70.26826
```

Based on true data:

```
apply(THETA, 2, summary)
```

```
##          theta_1   theta_2
## Min.    35.50314 37.80999
## 1st Qu. 45.35465 51.53327
## Median  47.36177 53.68602
## Mean    47.29978 53.68529
## 3rd Qu. 49.22875 55.82192
## Max.    60.94924 69.92354
```

Very similar for the most part.

COMPARE TO INFERENCE FROM FULL DATA

With missing data:

```
apply(SIGMA_WithMiss, 2, summary)

##           sigma_11   sigma_12   sigma_21   sigma_22
## Min.    74.61274 -10.83674 -10.83674  82.55346
## 1st Qu. 151.17000 110.33973 110.33973 189.31667
## Median 182.49663 141.85462 141.85462 231.76447
## Mean   194.75107 152.14494 152.14494 247.72255
## 3rd Qu. 224.42867 181.98838 181.98838 288.99033
## Max.   712.33562 600.36262 600.36262 960.62283
```

Based on true data:

```
apply(SIGMA, 2, summary)

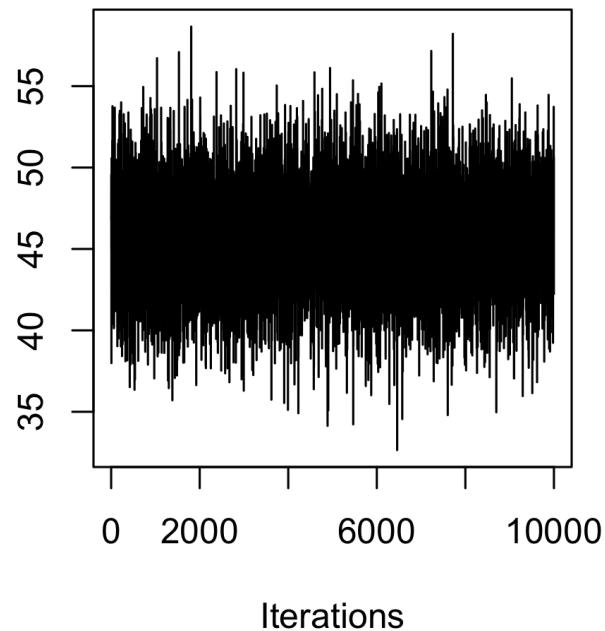
##           sigma_11   sigma_12   sigma_21   sigma_22
## Min.    79.44258 11.41663 11.41663  93.65776
## 1st Qu. 158.21469 113.23258 113.23258 203.21138
## Median 190.77854 144.74881 144.74881 244.56334
## Mean   202.34721 155.33355 155.33355 260.07072
## 3rd Qu. 234.77319 186.50429 186.50429 300.90761
## Max.   671.16538 613.88088 613.88088 947.39333
```

Also very similar. A bit more uncertainty in dimension of Y_{i2} because we have more missing data there.

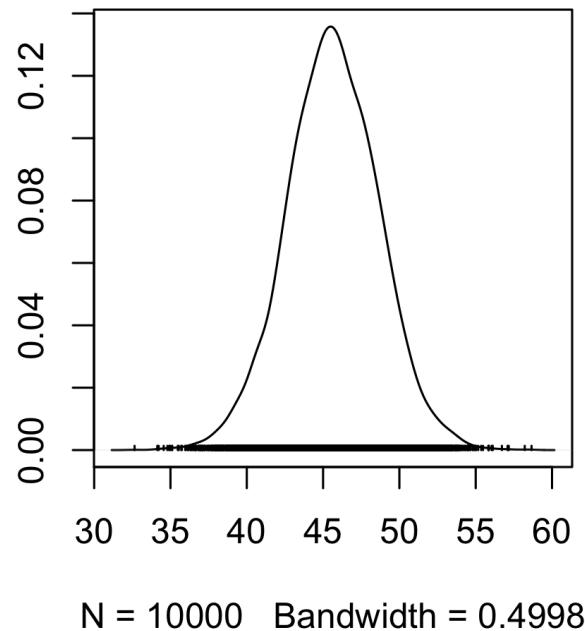
DIAGNOSTICS: TRACE PLOTS

```
plot(THETA_WithMiss.mcmc[, "theta_1"])
```

Trace of var1



Density of var1

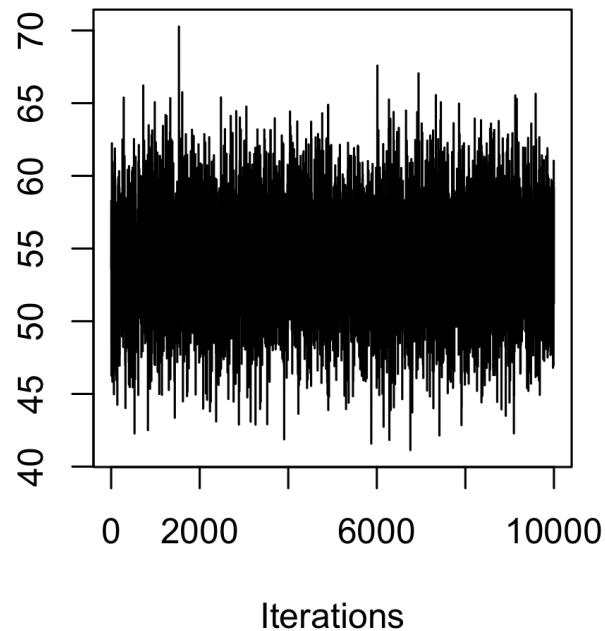


Looks good!

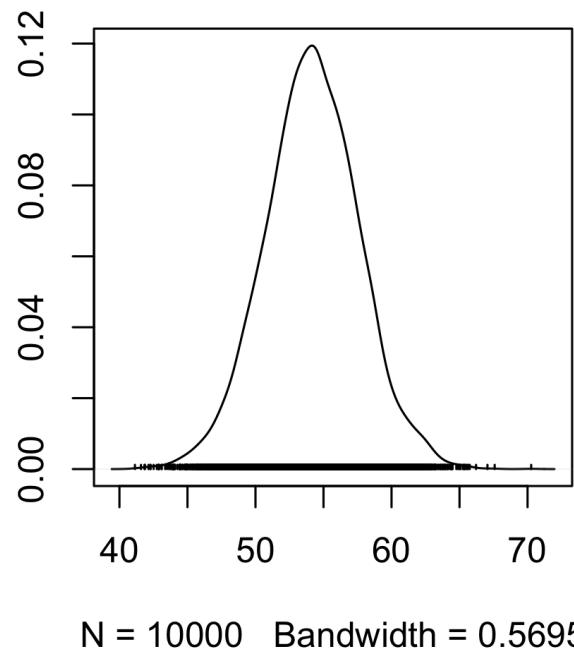
DIAGNOSTICS: TRACE PLOTS

```
plot(THETA_WithMiss.mcmc[, "theta_2"])
```

Trace of var1



Density of var1

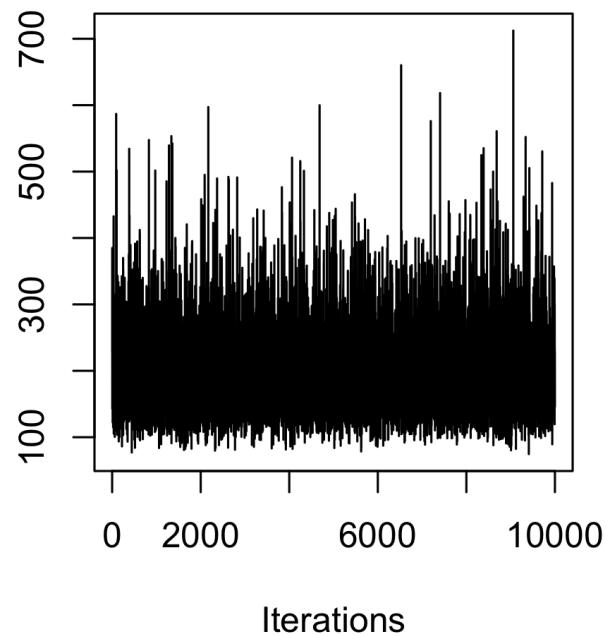


Looks good!

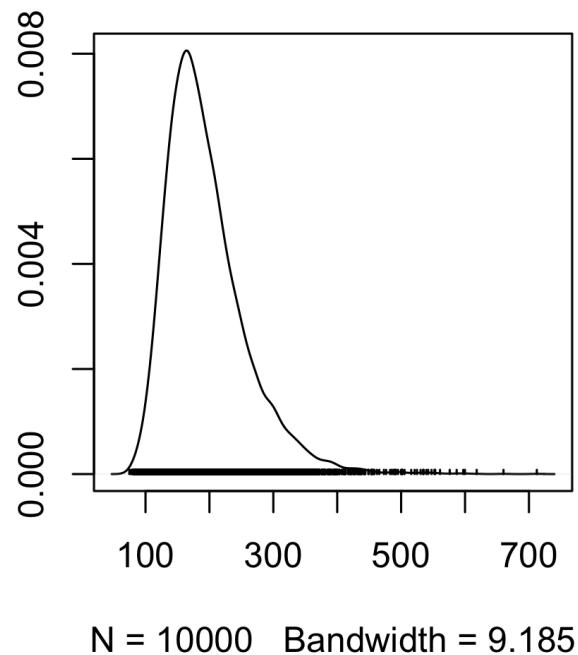
DIAGNOSTICS: TRACE PLOTS

```
plot(SIGMA_WithMiss.mcmc[, "sigma_11"])
```

Trace of var1



Density of var1

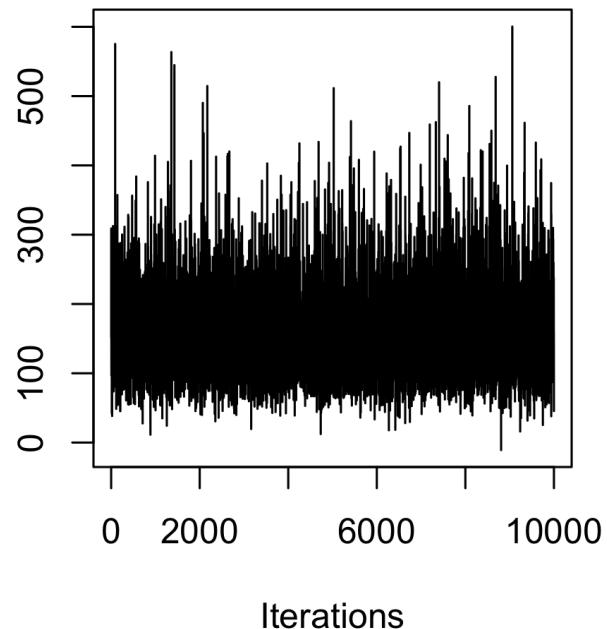


Looks good!

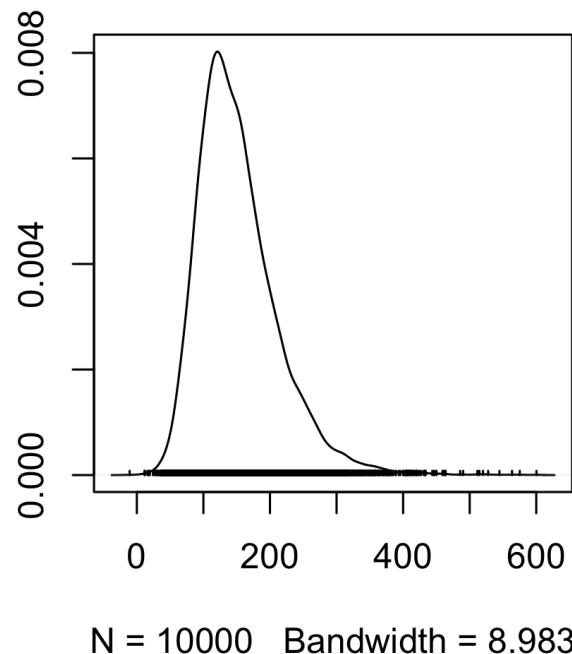
DIAGNOSTICS: TRACE PLOTS

```
plot(SIGMA_WithMiss.mcmc[, "sigma_12"])
```

Trace of var1



Density of var1

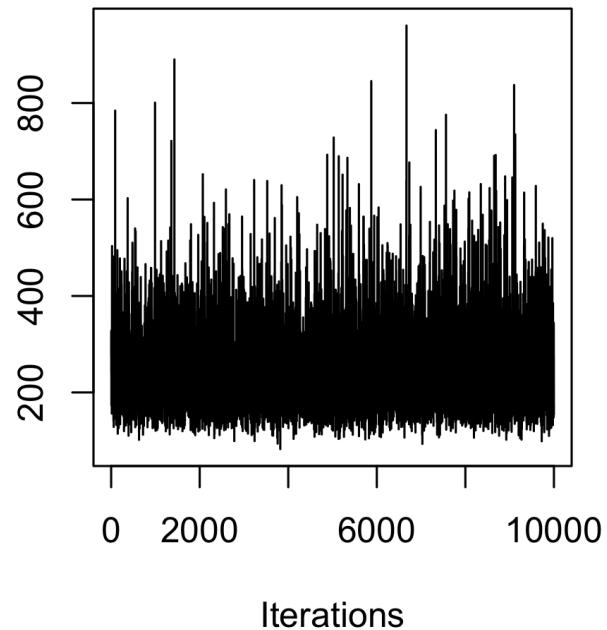


Looks good!

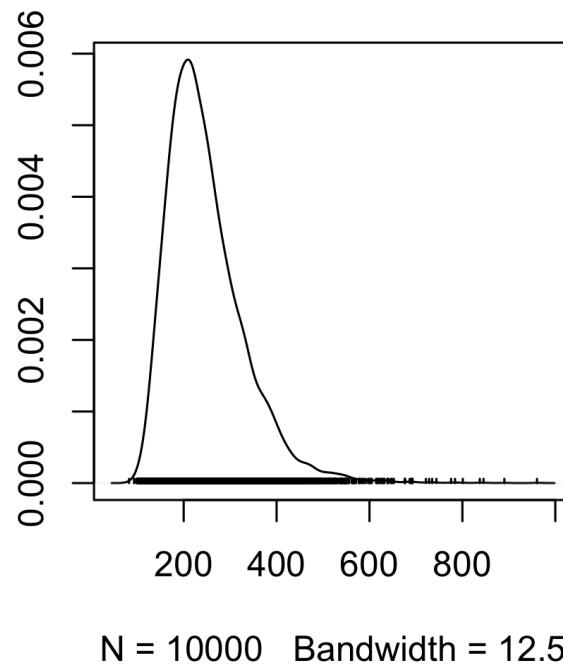
DIAGNOSTICS: TRACE PLOTS

```
plot(SIGMA_WithMiss.mcmc[, "sigma_22"])
```

Trace of var1



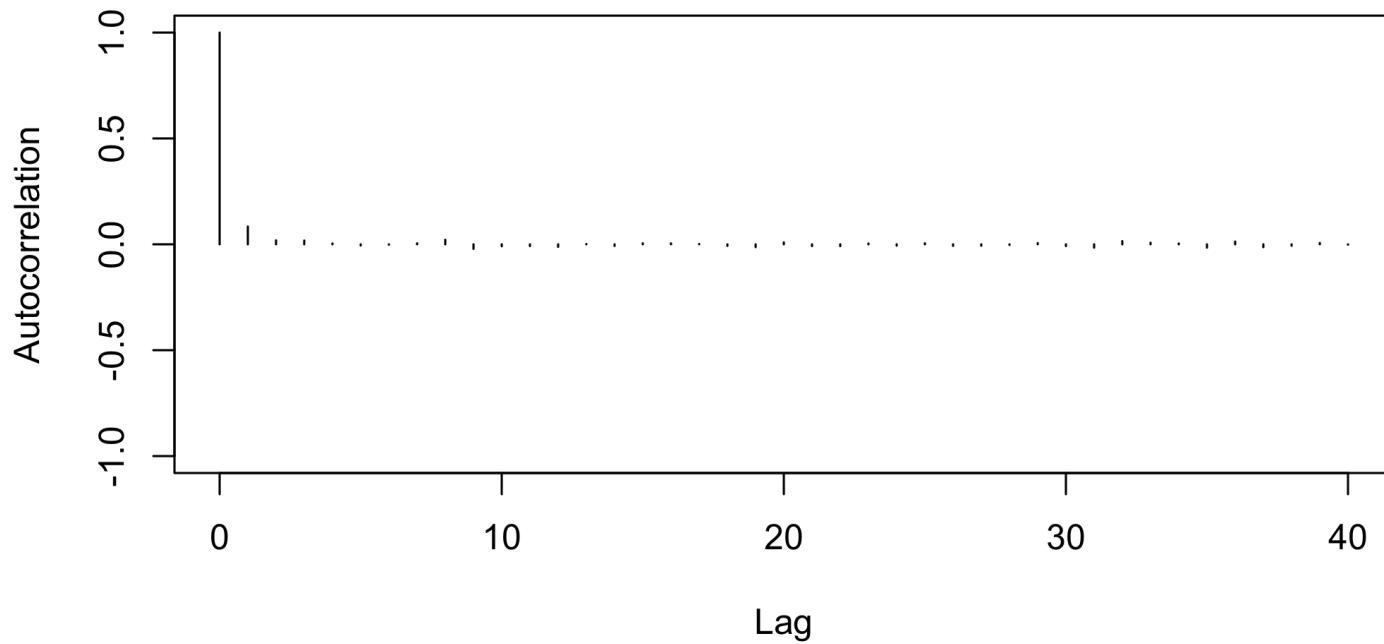
Density of var1



Looks good!

DIAGNOSTICS: AUTOCORRELATION

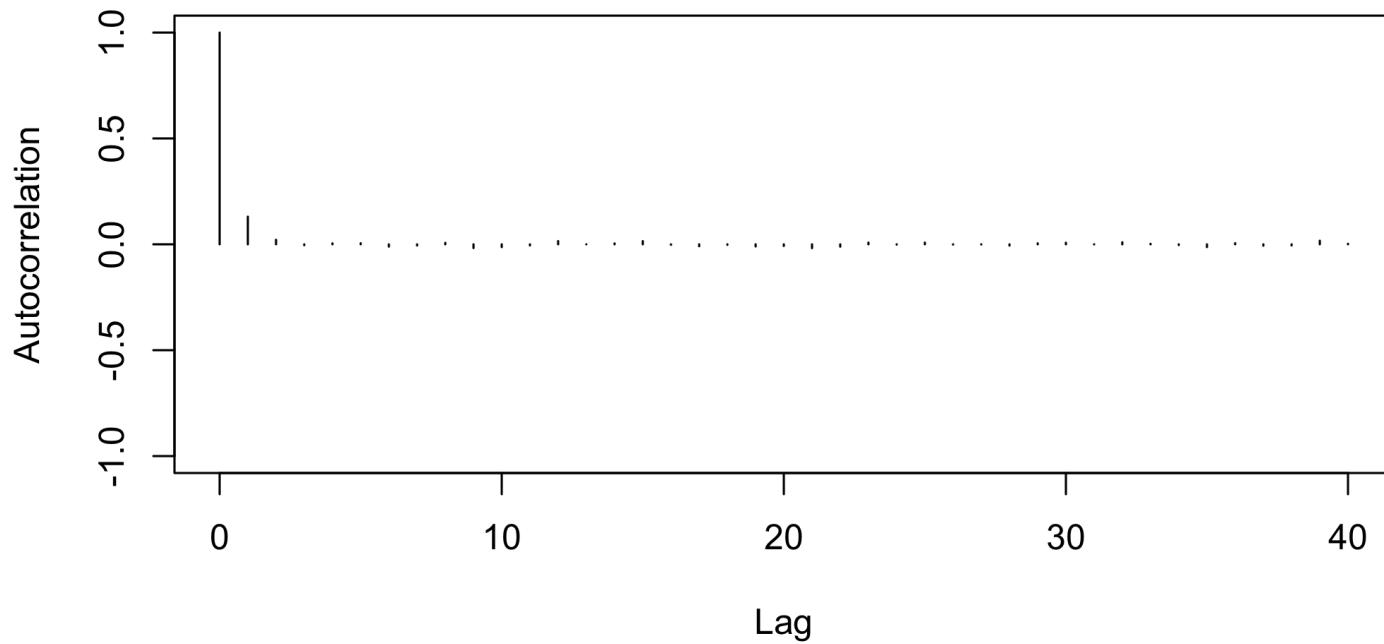
```
autocorr.plot(THETA_WithMiss.mcmc[, "theta_1"])
```



Looks good!

DIAGNOSTICS: AUTOCORRELATION

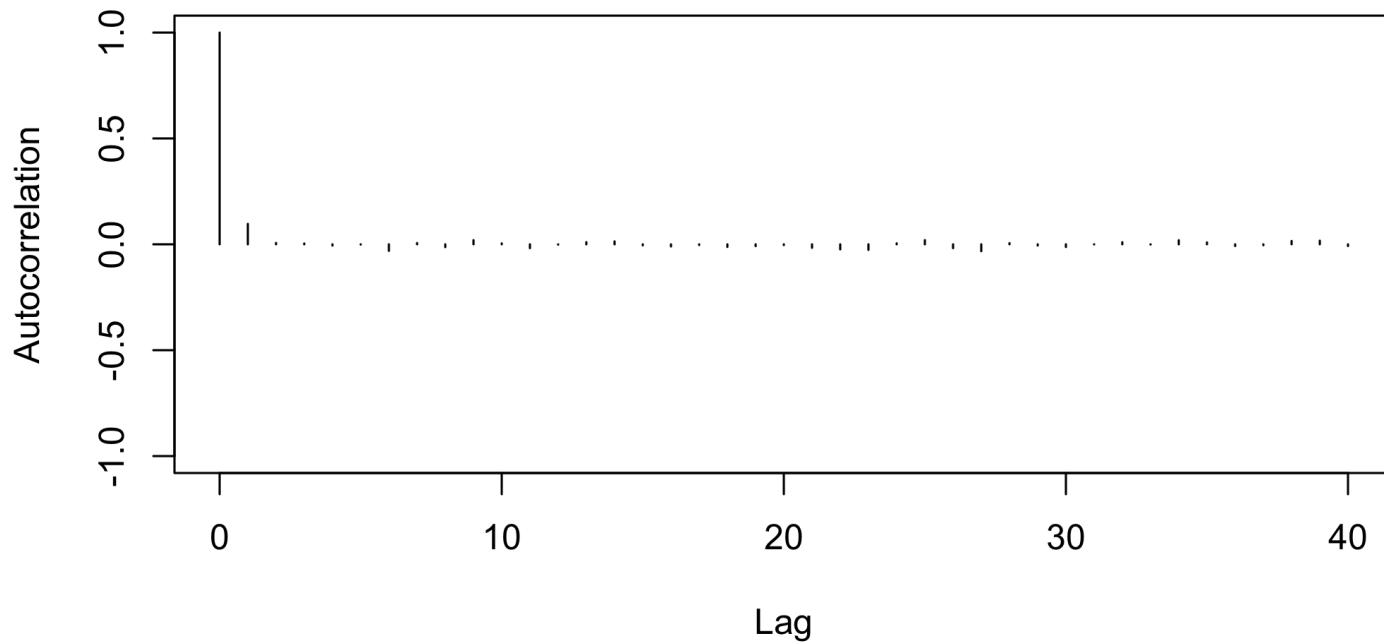
```
autocorr.plot(THETA_WithMiss.mcmc[, "theta_2"])
```



Looks good!

DIAGNOSTICS: AUTOCORRELATION

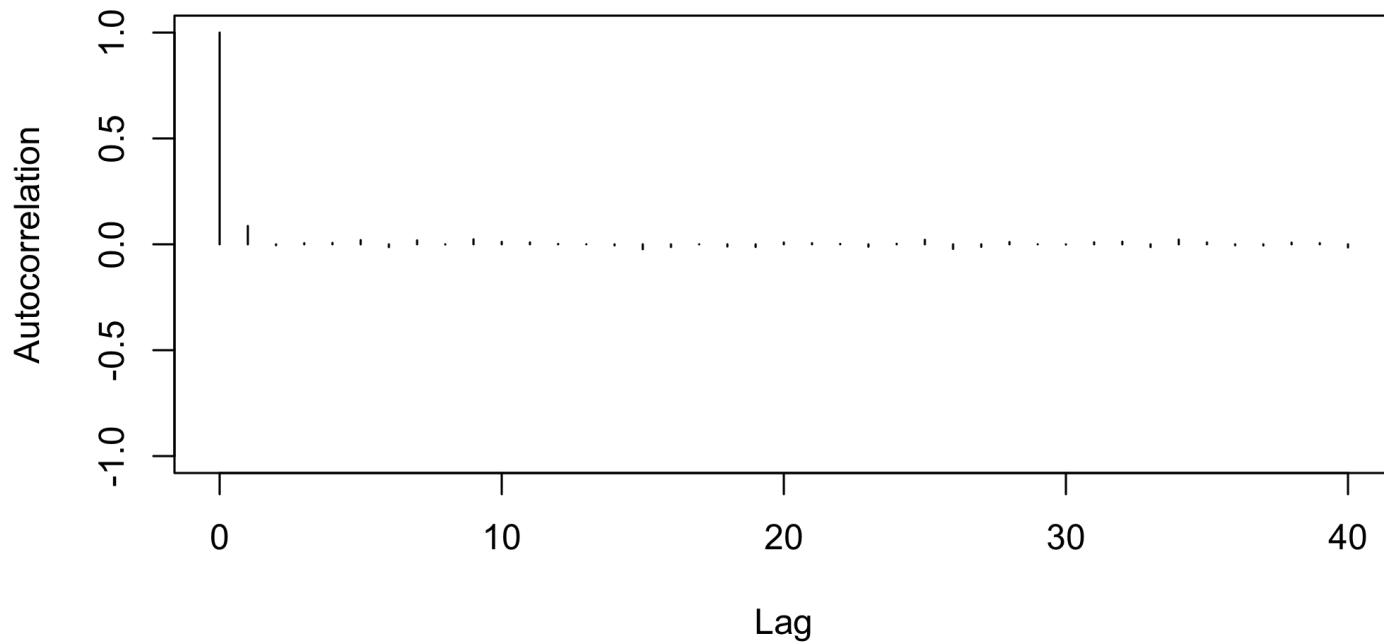
```
autocorr.plot(SIGMA_WithMiss.mcmc[, "sigma_11"])
```



Looks good!

DIAGNOSTICS: AUTOCORRELATION

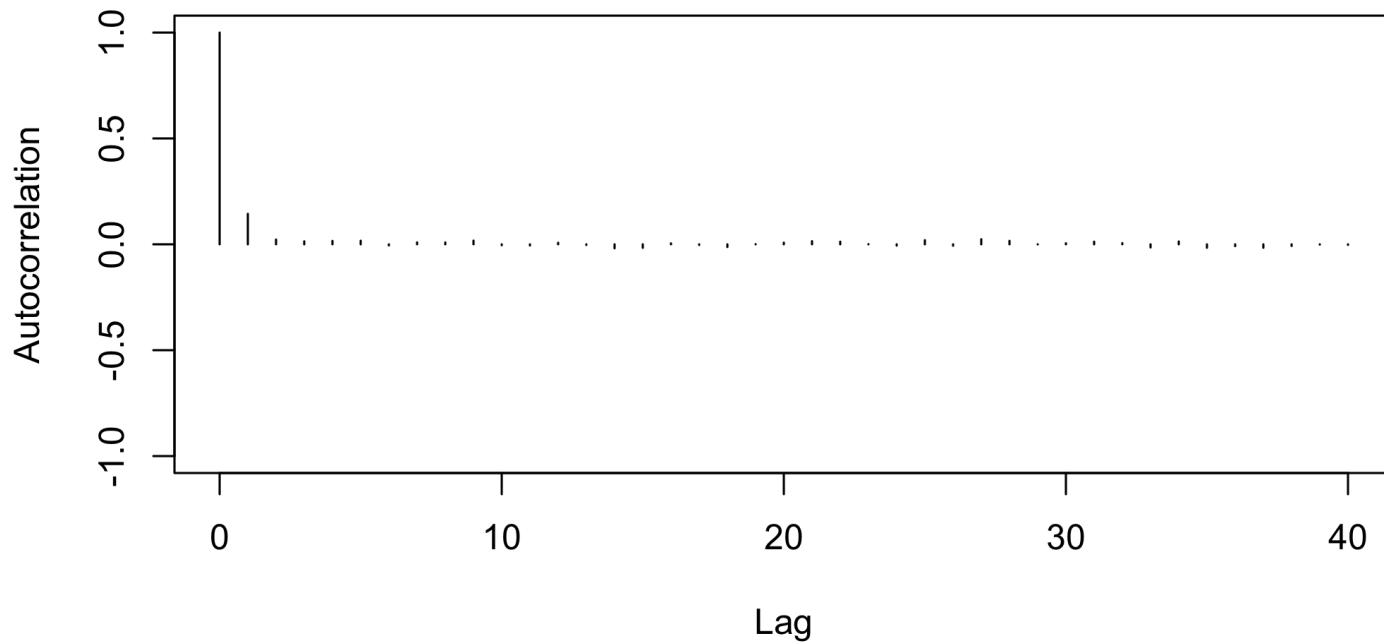
```
autocorr.plot(SIGMA_WithMiss.mcmc[, "sigma_12"])
```



Looks good!

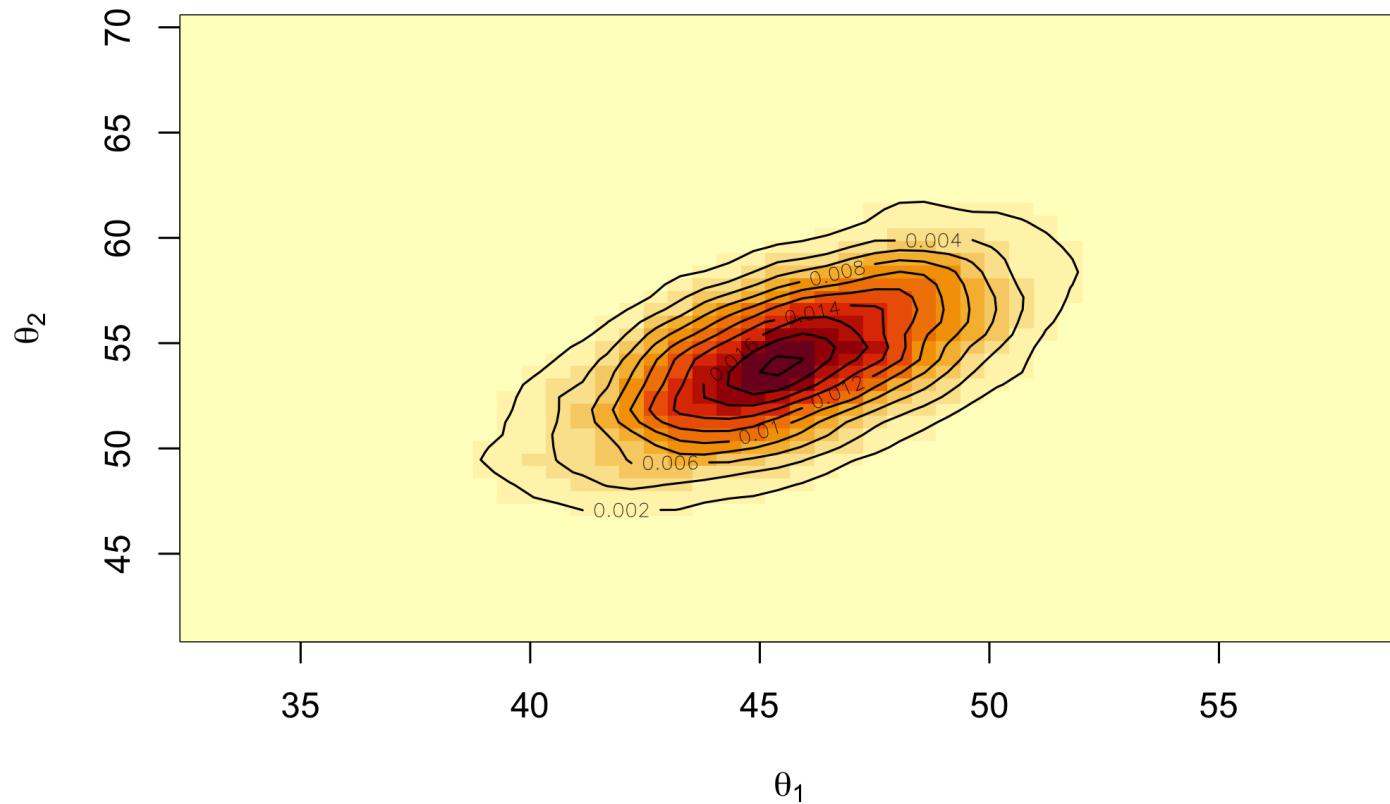
DIAGNOSTICS: AUTOCORRELATION

```
autocorr.plot(SIGMA_WithMiss.mcmc[, "sigma_22"])
```



Looks good!

POSTERIOR DISTRIBUTION OF THE MEAN



MISSING DATA VS PREDICTIONS FOR NEW OBSERVATIONS

- How about predictions for completely new observations?
- That is, suppose your original dataset plus sampling model is $\mathbf{y}_i = (y_{i,1}, y_{i,2})^T \sim \mathcal{N}_2(\boldsymbol{\theta}, \Sigma)$, $i = 1, \dots, n$.
- Suppose now you have n^* new observations with y_2^* values but no y_1^* .
- How can we predict $y_{i,1}^*$ given $y_{i,2}^*$, for $i = 1, \dots, n^*$?
- Well, we can view this as a "train → test" prediction problem rather than a missing data problem on an original data.

MISSING DATA VS PREDICTIONS FOR NEW OBSERVATIONS

- That is, given the posterior samples of the parameters, and the test values for $y_{i,2}^*$, draw from the posterior predictive distribution of $(y_{i,1}^* | y_{i,2}^*, \{(y_{1,1}, y_{1,2}), \dots, (y_{n,1}, y_{n,2})\})$.
- To sample from this predictive distribution, think of compositional sampling.
- That is, for each posterior sample of (θ, Σ) , sample from $(y_{i,1} | y_{i,2}, \theta, \Sigma)$, which is just from the form of the sampling distribution.
- In this case, $(y_{i,1} | y_{i,2}, \theta, \Sigma)$ is just a normal distribution derived from $(y_{i,1}, y_{i,2} | \theta, \Sigma)$, based on the conditional normal formula.
- No need to incorporate the prediction problem into your original Gibbs sampler!

WHAT'S NEXT?

MOVE ON TO THE READINGS FOR THE NEXT MODULE!